



Variable frequency drive, 400 V AC, 3-phase, 16 A, 7.5 kW, IP20/NEMA0, 7-digital display assembly, Setpoint potentiometer, Brake chopper, STO (Safe Torque Off, SIL2, PLd Cat 3)



Part no. DM1-34016NB-S20S-EM
Catalog No. 3-5012-006A

Delivery program

Product range			Variable frequency drives
Part group reference (e.g. DIL)			DM1
Rated operational voltage	U_e		400 V AC, 3-phase 480 V AC, 3-phase 500 V AC, 3-phase
Output voltage with V_e	U_2		400 V AC, 3-phase 480 V AC, 3-phase 500 V AC, 3-phase
Mains voltage (50/60Hz)	U_{LN}	V	380 (-10%) - 500 (+10%)
Rated operational current			
At 150% overload	I_e	A	16
At 110% overload	I_e	A	23
Note			Rated operational current for a switching frequency of 1 - 16 kHz and an ambient temperature of +50 °C for a 150% overload and +40 °C for a 110% overload
Assigned motor rating			
Note			for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm ⁻¹ at 50 Hz or 1800 min ⁻¹ at 60 Hz for PM motors
Note			Overload cycle for 60 s every 600 s
Note			at 400 V, 50 Hz
150 % Overload	P	kW	7.5
110 % Overload	P	kW	11
150 % Overload	I_M	A	15.2
110 % Overload	I_M	A	21.7
Note			at 500 V, 50 Hz
150 % Overload	P	kW	7.5
110 % Overload	P	kW	11
150 % Overload	I_M	A	12.1
110 % Overload	I_M	A	17.4
Note			at 480 V, 60 Hz
150 % Overload	P	HP	10
110 % Overload	P	HP	15
150 % Overload	I_M	A	14
110 % Overload	I_M	A	21
Degree of Protection			IP20/NEMA0
Interface/field bus (built-in)			Modbus RTU Modbus TCP BACnet MS/TP Ethernet IP BACnet TCP
Fieldbus connection (optional)			Profibus, CAN, DeviceNet, SmartwireDT
Fitted with			7-digital display assembly Setpoint potentiometer Brake chopper
Parameterization			Keypad Fieldbus Power Xpert inControl

Frame size			FS2
Connection to SmartWire-DT			yes in conjunction with DXG-NET-SWD SmartWire DT module

Technical data

General

Standards			General requirements: IEC/EN 61800-2 EMV requirements: IEC/EN 61800-3 Safety requirements: IEC/EN 61800-5-1:2007/A1:2017; UL 61800-5-1:2012 (Rev. 2018), CSA C22.2 No. 274-17:2017
Certifications			CE, UL, cUL, c-Tick, UkrSEPRO, EAC
Production quality			RoHS, ISO 9001
Climatic proofing	ρ_w	%	< 95%, average relative humidity (RH), non-condensing, non-corrosive
Air quality			3C2, 3S2
Ambient temperature			
Operating ambient temperature min.		°C	-10
Operating ambient temperature max.		°C	+50
operation (110 % overload)	θ	°C	-10 - +40 (max. +55 with 1 % derating per Kelvin temperature rise) °C
			Operation with 110 % overload (1 min./10 min.): -10 to +40 (max. +55 with 1% derating per Kelvin above limit) Operation with 150% overload (1 min./10 min.): -10 to +50 (max. +60 with 1% derating per Kelvin above limit) -20 with cold-weather mode
Storage	θ	°C	-40 - +70
Overvoltage category			III
Pollution degree			2
Radio interference level			
Radio interference class (EMC)			C1 (with external filter, for conducted emissions only), C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary.
Environment (EMC)			1st and 2nd environments as per EN 61800-3
Mechanical shock resistance		g	EN 61800-5-1, EN 60068-2-6: 10 - 150 Hz Amplitude: 0,75 mm (peak) bei 10 - 57 Hz Maximum acceleration amplitude: 1 g at 57 – 150 Hz
Mounting position			Vertical
Altitude		m	0 - 1000 m above sea level Above 1000 m: 1% derating for every 100 m max. 3000 m (2000 m for Corner Grounded TN Systems)
Degree of Protection			IP20/NEMA0
Protection against direct contact			BGV A3 (VBG4, finger- and back-of-hand proof)

Main circuit

Supply			
Rated operational voltage	U_e		400 V AC, 3-phase 480 V AC, 3-phase 500 V AC, 3-phase
Mains voltage (50/60Hz)	U_{LN}	V	380 (-10%) - 500 (+10%)
Input current (150% overload)	I_{LN}	A	19.2
Input current (110% overload)	I_{LN}	A	27.6
System configuration			TN-S, TN-C, TN-C-S, TT, IT
Supply frequency	f_{LN}	Hz	50/60
Frequency range	f_{LN}	Hz	45–66 ($\pm 0\%$)
Mains switch-on frequency			Maximum of one time every 60 seconds
Mains current distortion	THD	%	40
Rated conditional short-circuit current	I_q	kA	< 100
Power section			
Function			Variable frequency drive with internal DC link, DC link choke and IGBT inverter
Overload current (150% overload)	I_L	A	24
Overload current (110% overload)	I_L	A	25.3
max. starting current (High Overload)	I_H	%	200
Note about max. starting current			for 2 seconds every 20 seconds
Output voltage with V_e	U_2		400 V AC, 3-phase 480 V AC, 3-phase

			500 V AC, 3-phase
Output Frequency	f_2	Hz	0 - 50/60 (max. 400)
Switching frequency	f_{PWM}	kHz	4 adjustable 1 - 16
Operation Mode			U/f control Speed control with slip compensation sensorless vector control (SLV) Torque regulation PM motors
Frequency resolution (setpoint value)	Δf	Hz	0.01
Rated operational current			
At 150% overload	I_e	A	16
At 110% overload	I_e	A	23
Note			Rated operational current for a switching frequency of 1 - 16 kHz and an ambient temperature of +50 °C for a 150% overload and +40 °C for a 110% overload
Motor current limit	I	A	0.1 - 2 x I_H (CT)
Power loss			
Heat dissipation at rated operational current $I_e = 150\%$	P_V	W	216.4
Heat dissipation at rated operational current $I_e = 110\%$	P_V	W	332.4
Heat dissipation at current/speed [%]			
Current = 100%			
Speed = 0 %	P_V	W	230
Speed = 50 %	P_V	W	115.2
Speed = 90 %	P_V	W	317.7
Current = 50 %			
Speed = 0 %	P_V	W	274.2
Speed = 50 %	P_V	W	127.7
Speed = 90 %	P_V	W	158.2
Current = 50 %			
Speed = 0 %	P_V	W	83
Speed = 50 %	P_V	W	95.6
Fan			temperature controlled
Internal fan delivery rate		m^3/h	64
Fitted with			7-digital display assembly Setpoint potentiometer Brake chopper
Safety function			STO (Safe Torque Off, SIL2, PLd Cat 3)
Frame size			FS2
Motor feeder			
Note			for normal internally and externally ventilated 4 pole, three-phase asynchronous motors with 1500 rpm^{-1} at 50 Hz or 1800 min^{-1} at 60 Hz for PM motors
Note			Overload cycle for 60 s every 600 s
Note			at 400 V, 50 Hz
150 % Overload	P	kW	7.5
110 % Overload	P	kW	11
Note			at 500 V, 50 Hz
150 % Overload	P	kW	7.5
110 % Overload	P	kW	11
Note			at 480 V, 60 Hz
150 % Overload	P	HP	10
110 % Overload	P	HP	15
Braking function			
Standard braking torque			max. 30 % M_N
DC braking torque			adjustable to 150 %
Braking torque with external braking resistance			Max. 100% of rated operational current I_e with external braking resistor
minimum external braking resistance	R_{min}	Ω	35
Switch-on threshold for the braking transistor	U_{DC}	V	800 V DC

DC braking	%	I/I _e	≤ 150, adjustable
Control section			
External control voltage	U _c	V	24 V DC (max. 100 mA options incl.)
Reference voltage	U _s	V	10 V DC (max. 10 mA)
Analog inputs			1, can be parameterized, 0–10 V DC, 2–10 V DC, 0/4–20 mA
Analog outputs			1, parameterizable, 0 - 10 V
Digital inputs			4, parameterizable, max. 30 V DC
Relay outputs			2, parameterizable, 1 changeover contacts and 1 N/O, 3 A (240 VAC) / 3 A (24 VDC)
Interface/field bus (built-in)			Modbus RTU Modbus TCP BACnet MS/TP Ethernet IP BACnet TCP
Expansion slots			1

Assigned switching and protective elements

Power Wiring			
Safety device (fuse or miniature circuit-breaker)			
			PKZM0-16
IEC (Type B, gG), 150 %			
IEC (Type B, gG), 110 %			PKZM0-25
UL (Class CC or J)		A	32
Mains contactor			
150 % overload (CT/I _H , at 50 °C)			DILM7-10 (230V50HZ,240V60HZ)
110 % overload (VT/I _L , at 40 °C)			DILM17-10 (230V50HZ,240V60HZ)
Main choke			
150 % overload (CT/I _H , at 50 °C)			DX-LN3-016
110 % overload (VT/I _L , at 40 °C)			DX-LN3-025
Radio interference suppression filter (external, 150 %)			DX-EMC34-030
Radio interference suppression filter (external, 110 %)			DX-EMC34-030
Radio interference suppression filter, low leakage currents (external, 150 %)			DX-EMC34-030-L
Radio interference suppression filter, low leakage currents (external, 110 %)			DX-EMC34-030-L
Note regarding radio interference suppression filter			Optional external radio interference suppression filter for longer motor cable lengths and for use in different EMC environments
DC link connection			
Braking resistance			
10 % duty factor (DF)			DX-BR040-3K1
20 % duty factor (DF)			DX-BR040-5K1
40 % duty factor (DF)			DX-BR047-9K2
Notes concerning braking resistances:			The brake resistors are assigned based on the maximum rated power of the variable frequency drive. Additional brake resistors and designs (e.g. different duty cycles) are available upon request.
Motor feeder			
motor choke			
150 % overload (CT/I _H , at 50 °C)			DX-LM3-016
110 % overload (VT/I _L , at 40 °C)			DX-LM3-035
Sine filter			
150 % overload (CT/I _H , at 50 °C)			DX-SIN3-016
110 % overload (VT/I _L , at 40 °C)			DX-SIN3-023
All-pole sine filter			
150 % overload (CT/I _H , at 50 °C)			DX-SIN3-024-A
110 % overload (VT/I _L , at 40 °C)			DX-SIN3-024-A

Design verification as per IEC/EN 61439

Technical data for design verification			
Rated operational current for specified heat dissipation	I _n	A	23
Equipment heat dissipation, current-dependent	P _{vid}	W	332.4
Operating ambient temperature min.		°C	-10
Operating ambient temperature max.		°C	50

IEC/EN 61439 design verification		
10.2 Strength of materials and parts		
10.2.2 Corrosion resistance		Meets the product standard's requirements.
10.2.3.1 Verification of thermal stability of enclosures		Meets the product standard's requirements.
10.2.3.2 Verification of resistance of insulating materials to normal heat		Meets the product standard's requirements.
10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects		Meets the product standard's requirements.
10.2.4 Resistance to ultra-violet (UV) radiation		Meets the product standard's requirements.
10.2.5 Lifting		Does not apply, since the entire switchgear needs to be evaluated.
10.2.6 Mechanical impact		Does not apply, since the entire switchgear needs to be evaluated.
10.2.7 Inscriptions		Meets the product standard's requirements.
10.3 Degree of protection of ASSEMBLIES		Does not apply, since the entire switchgear needs to be evaluated.
10.4 Clearances and creepage distances		Meets the product standard's requirements.
10.5 Protection against electric shock		Does not apply, since the entire switchgear needs to be evaluated.
10.6 Incorporation of switching devices and components		Does not apply, since the entire switchgear needs to be evaluated.
10.7 Internal electrical circuits and connections		Is the panel builder's responsibility.
10.8 Connections for external conductors		Is the panel builder's responsibility.
10.9 Insulation properties		
10.9.2 Power-frequency electric strength		Is the panel builder's responsibility.
10.9.3 Impulse withstand voltage		Is the panel builder's responsibility.
10.9.4 Testing of enclosures made of insulating material		Is the panel builder's responsibility.
10.10 Temperature rise		The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices.
10.11 Short-circuit rating		Is the panel builder's responsibility. The specifications for the switchgear must be observed.
10.12 Electromagnetic compatibility		Is the panel builder's responsibility. The specifications for the switchgear must be observed.
10.13 Mechanical function		The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.

Technical data ETIM 7.0

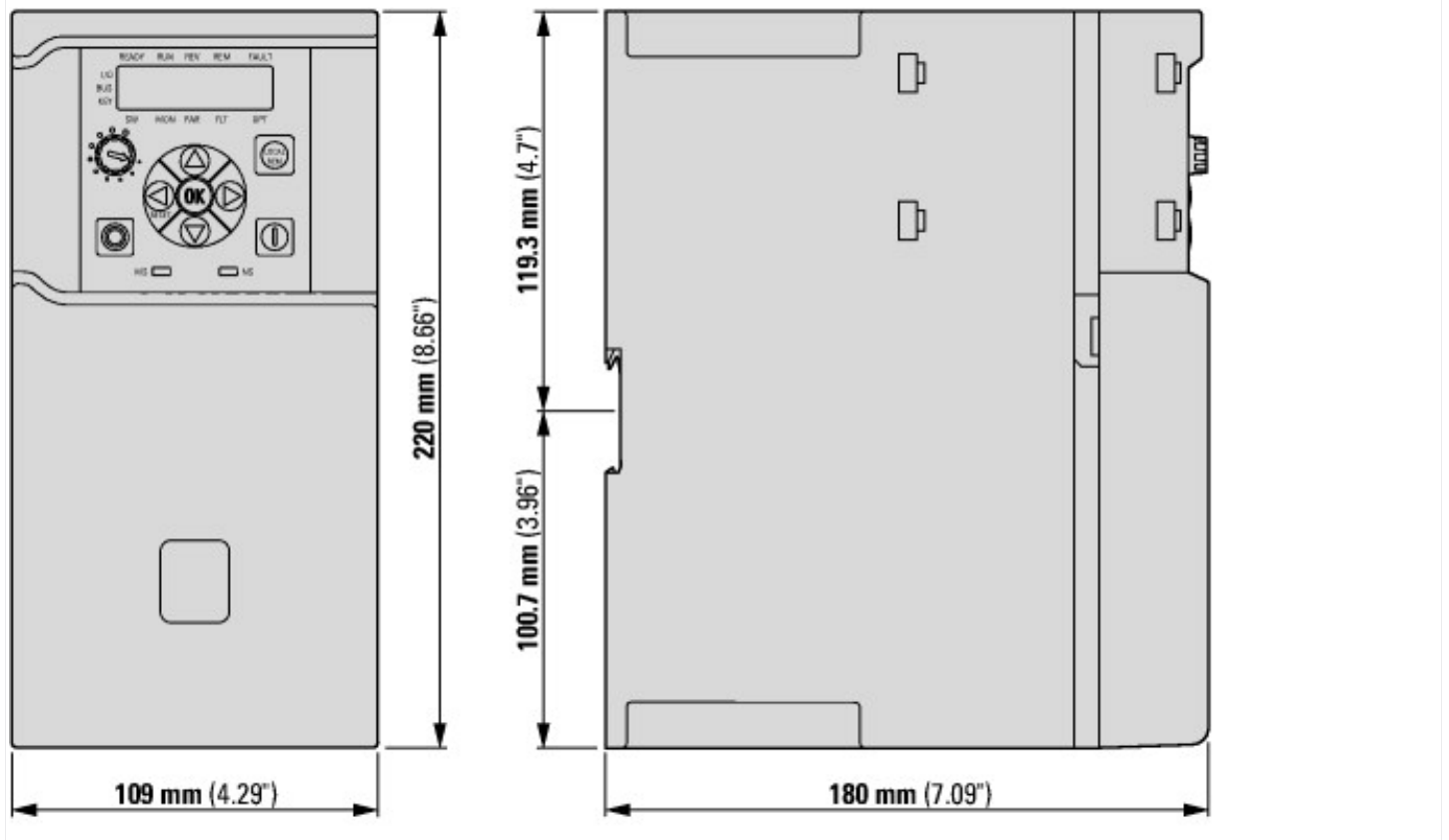
Low-voltage industrial components (EG000017) / Frequency converter =< 1 kV (EC001857)			
Electric engineering, automation, process control engineering / Electrical drive / Static frequency converter / Static frequency converter = < 1 kV (ecl@ss10.0.1-27-02-31-01 [AKE177014])			
Mains voltage	V		323 - 528
Mains frequency			50/60 Hz
Number of phases input			3
Number of phases output			3
Max. output frequency	Hz		400
Max. output voltage	V		500
Nominal output current I2N	A		23
Max. output at quadratic load at rated output voltage	kW		11
Max. output at linear load at rated output voltage	kW		7.5
Relative symmetric net frequency tolerance	%		10
Relative symmetric net voltage tolerance	%		10
Number of analogue outputs			1
Number of analogue inputs			1
Number of digital outputs			0
Number of digital inputs			4
With control unit			Yes
Application in industrial area permitted			Yes
Application in domestic- and commercial area permitted			No
Supporting protocol for TCP/IP			Yes
Supporting protocol for PROFIBUS			Yes
Supporting protocol for CAN			Yes
Supporting protocol for INTERBUS			No
Supporting protocol for ASI			No
Supporting protocol for KNX			No

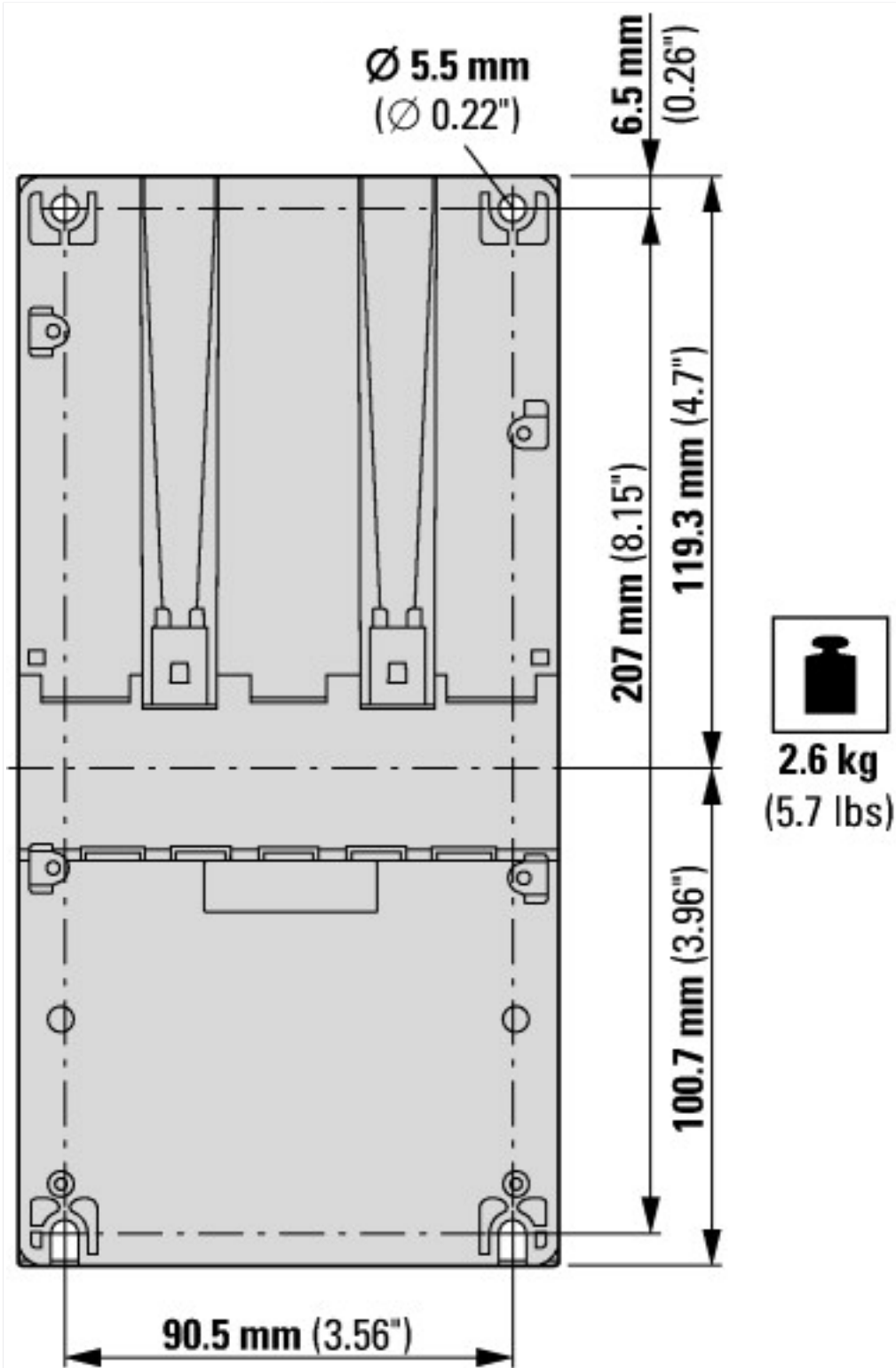
Supporting protocol for MODBUS		Yes
Supporting protocol for Data-Highway		No
Supporting protocol for DeviceNet		Yes
Supporting protocol for SUCONET		No
Supporting protocol for LON		No
Supporting protocol for PROFINET IO		No
Supporting protocol for PROFINET CBA		No
Supporting protocol for SERCOS		No
Supporting protocol for Foundation Fieldbus		No
Supporting protocol for EtherNet/IP		Yes
Supporting protocol for AS-Interface Safety at Work		No
Supporting protocol for DeviceNet Safety		No
Supporting protocol for INTERBUS-Safety		No
Supporting protocol for PROFIsafe		No
Supporting protocol for SafetyBUS p		No
Supporting protocol for BACnet		Yes
Supporting protocol for other bus systems		Yes
Number of HW-interfaces industrial Ethernet		1
Number of interfaces PROFINET		0
Number of HW-interfaces RS-232		0
Number of HW-interfaces RS-422		0
Number of HW-interfaces RS-485		1
Number of HW-interfaces serial TTY		0
Number of HW-interfaces USB		0
Number of HW-interfaces parallel		0
Number of HW-interfaces other		1
With optical interface		No
With PC connection		Yes
Integrated breaking resistance		Yes
4-quadrant operation possible		Yes
Type of converter		U converter
Degree of protection (IP)		IP20
Degree of protection (NEMA)		Other
Height	mm	220
Width	mm	109
Depth	mm	180

Approvals

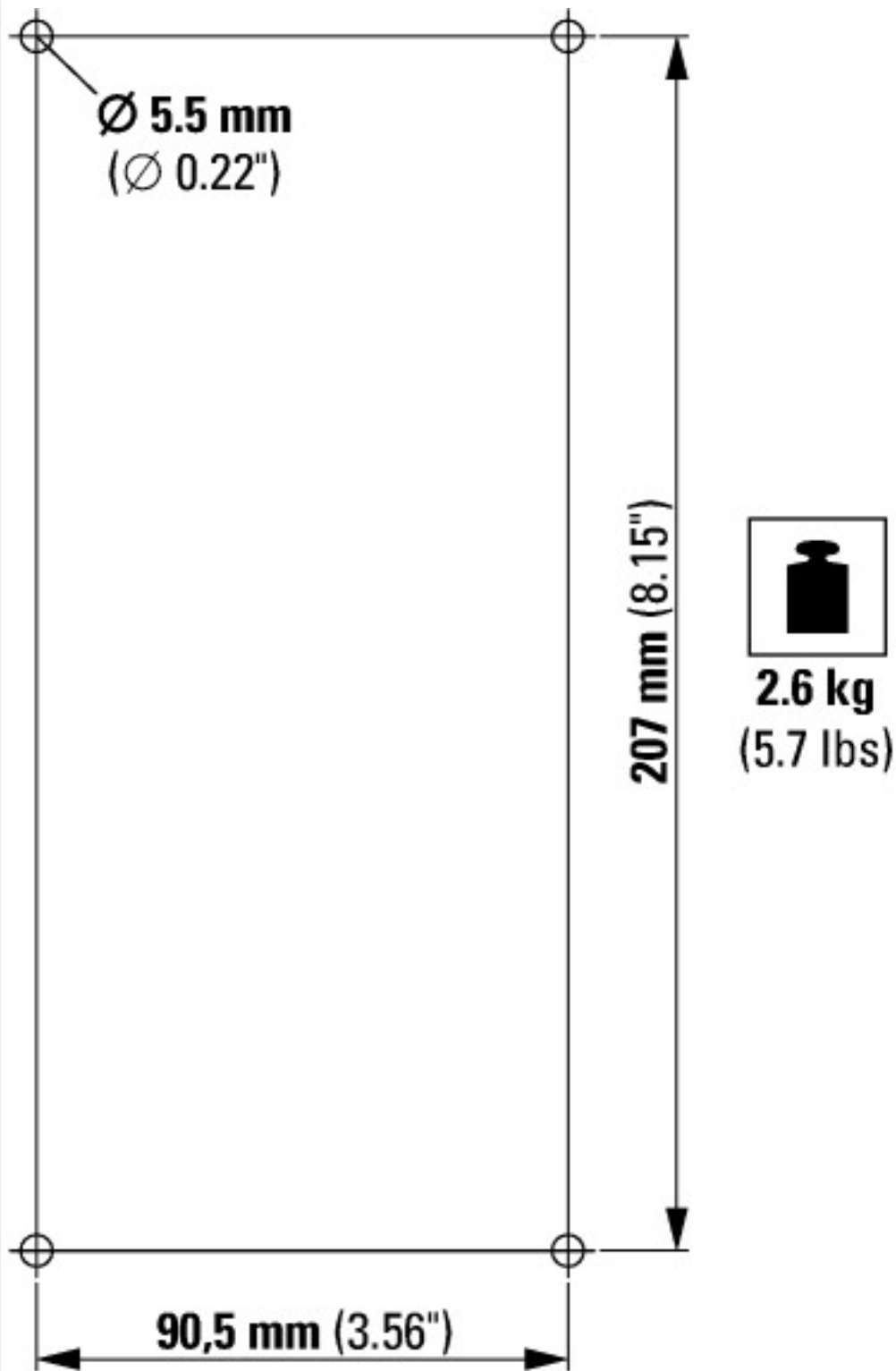
Product Standards		UL508C, CSA-C22.2 No. 274-13; IEC/EN61800-3; IEC/EN61800-5; CE marking
UL File No.		E134360
UL Category Control No.		NMMS, NMMS7
CSA File No.		UL report applies to both US and Canada
North America Certification		UL listed, certified by UL for use in Canada
Suitable for		Branch circuits
Max. Voltage Rating		3-500 V AC IEC: TN-S UL/CSA: 'Y' (Solidly Grounded Wey)
Degree of Protection		IP20/NEMA0

Dimensions





Back view



Drilling patterns