

# Variable Frequency Drive, 3-/3- 400 V, 9.5 A, 4 kW, EMC-Filter, Brake-Chopper



Specification for general requirements: IEC/EN 61800-2 EMC requirements: IEC/EN 61800-3

Part no. DC1-349D5FB-A20N Article no. 169487 Catalog No. DC1-349D5FB-A20N

### **Technical data**

General
Standards

			EMC requirements: IEC/EN 61800-3 Safety requirements: IEC/EN 61800-5-1
Certifications			CE, UL, cUL, c-Tick, UkrSepro, EAC
Production quality			RoHS, ISO 9001
Climatic proofing	$\rho_{\text{W}}$	%	< 95%, average relative humidity (RH), non-condensing, non-corrosive
Ambient temperature			
operation (150 % overload)	θ	°C	-10 - +50
Storage	θ	°C	-40 - +60
Radio interference level			
Radio interference class (EMC)			C2, C3, depending on the motor cable length, the connected load, and ambient conditions. External radio interference suppression filters (optional) may be necessary.
Environment (EMC)			1st and 2nd environments as per EN 61800-3
maximum motor cable length	I	m	C2 ≤ 5 m C3 ≤ 25 m
Mounting position			Vertical
Altitude		m	0 - 1000 m above sea level Above 1000 m: 1% derating for every 100 m max. 4000 m
Degree of Protection			IP20/NEMA 0
Protection against direct contact			BGV A3 (VBG4, finger- and back-of-hand proof)
Main circuit			
Supply			
Rated operational voltage	U <sub>e</sub>		400 V AC, 3-phase 480 V AC, 3-phase
Mains voltage (50/60Hz)	U <sub>LN</sub>	V	380 (-10%) - 480 (+10%)
Input current (150% overload)	I <sub>LN</sub>	Α	11.5
System configuration			AC supply systems with earthed center point
Supply frequency	$f_{LN}$	Hz	50/60
Frequency range	$f_{LN}$	Hz	48 - 62
Mains switch-on frequency			Maximum of one time every 30 seconds
Power section			
Function			Frequency inverter with internal DC link and IGBT inverter
Overload current (150% overload)	IL	Α	14.25
max. starting current (High Overload)	I <sub>H</sub>	%	175
Note about max. starting current			for 2 seconds every 20 seconds
Output voltage with $V_{\rm e}$	U <sub>2</sub>		400 V AC, 3-phase 480 V AC, 3-phase
Output Frequency	f <sub>2</sub>	Hz	0 - 50/60 (max. 500)
Switching frequency	f <sub>PWM</sub>	kHz	16 adjustable 4 - 32 (audible)
Operation Mode			U/f control Speed control with slip compensation
Frequency resolution (setpoint value)	Δf	Hz	0.1
Rated operational current			
At 150% overload	I <sub>e</sub>	Α	9.5
Note			Rated operational current at an operating frequency of 16 kHz and an ambient air temperature of +50 $^{\circ}\text{C}$
Power loss			

Note  Note  Note  Note  Note  Note  150 Noverload	Heat dissipation at rated operational current $\rm I_{\rm e}$ =150 $\%$	$P_{V}$	W	136
Maximum leakage current to ground (PE) without motor   Ige	Efficiency	η	%	96.6
Frame sto  Note  N	Maximum leakage current to ground (PE) without motor		mA	<1
Note				Brake chopper
Note  Note  Note  Note  Note  Note  150 Noverload	Frame size			FS2
Note	Motor feeder			
Note	Note			
150 % Overload	Note			Overload cycle for 60 s every 600 s
Note   150 % Overload	Note			at 400 V, 50 Hz
150 % Overload	150 % Overload	P	kW	4
maximum permissible cable length	Note			at 440 - 480 V, 60 Hz
Apparent power  Apparent power at rated operation 400 V S KVA 5.8  Apparent power at rated operation 480 V S KVA 7.9  Braking function  Standard braking torque  Braking torque with external braking resistance  Braking torque  Braking torqu	150 % Overload	P	HP	5
Apparent power at rated operation 400 V S kVA Apparent power at rated operation 480 V S kVA Apparent power at rated operation 480 V S kVA Apparent power at rated operation 480 V S kVA Apparent power at rated operation 480 V S kVA Braking function  Standard braking torque  D C braking torque Braking torque with external braking resistance minimum external braking resistance minimum external braking resistance Mu C V 780 V D C  Control Section  Reference voltage Vu 10 V DC (max. 10 mA) Analog inputs Analog outputs Digital inputs Digital inputs Digital inputs Digital inputs Digital voltputs Reference voltage Analog voltputs Reference voltage Analog voltputs Reference voltage Analog voltputs Reference voltage Vu 10 V DC (max. 10 mA) Analog inputs Analog voltputs Digital voltputs Reference voltage Vu 2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 3, parameterizable, 0 - 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 4, parameterizable, 0 - 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 5, parameterizable, 0 - 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 6, parameterizable, 0 - 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 9, parameterizable, 0 - 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Apparent voltage Vu 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 9, parameterizable, 0 - 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 10 V DC, 0/4 - 20 mA Analog voltputs Reference voltage Vu 10 V DC, 0	maximum permissible cable length	ı	m	screened, with motor choke: 200 unscreened: 150
Apparent power at rated operation 480 V Braking function  Standard braking torque  DC braking torque  Braking torque with external braking resistance minimum external braking resistance minimum external braking resistance minimum external braking transistor  Du <sub>D</sub> Switch-on threshold for the braking transistor  Du <sub>D</sub>	Apparent power			
Braking function Standard braking torque  DC braking torque Braking torque with external braking resistance minimum external braking resistance minimum external braking resistance minimum external braking resistance  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of rated operational current I <sub>6</sub> with external braking resistor  Max. 100% of value operational current I <sub>6</sub> with external braking resistor  Max. 100% of value operational current I <sub>6</sub> with external braking resistor  Max. 100% of value operational current I <sub>6</sub> with external braking resistor  Max. 100% of value operational current I <sub>6</sub> with external braking resistor  Max. 100% of value operational current I <sub>6</sub> with external braking resistor  Max. 100% of value operational current I <sub>6</sub> with value department I <sub>6</sub> with VDC,	Apparent power at rated operation 400 V	S	kVA	6.58
Standard braking torque  DC braking torque  Braking torque with external braking resistance minimum external braking resistance minimum external braking resistance  Max. 100% of rated operational current I <sub>e</sub> with external braking resistor  Max. 100% of rated operational current I <sub>e</sub> with external braking resistor  Max. 100% of rated operational current I <sub>e</sub> with external braking resistor  Max. 100% of rated operational current I <sub>e</sub> with external braking resistor  Max. 100% of rated operational current I <sub>e</sub> with external braking resistor  Max. 100% of rated operational current I <sub>e</sub> with external braking resistor  Max. 100% of rated operational current I <sub>e</sub> with external braking resistor  Max. 100% of rated operational current I <sub>e</sub> with external braking resistor  Max. 100% of rated operational current I <sub>e</sub> with external braking resistor  Max. 100% of rated operational current I <sub>e</sub> with external braking resistor  Max. 100% OF Company of Tables	Apparent power at rated operation 480 V	S	kVA	7.9
DC braking torque Braking torque with external braking resistance minimum external braking resistance minimum external braking resistance minimum external braking resistance  Rmin  Upc V780 V DC  Control section  Reference voltage  Us V10 V DC (max. 10 mA)  Analog outputs  Analog outputs  Digital outputs  Interface/field bus (built-in)  Assigned switching and protective elements  Perwer Wiring  IEC (Type B, gB, 150 %  UL (Class CC or J) 150 % overload (CT/I <sub>H</sub> , at 50 °C)  Motor feeder  150 % overload (CT/I <sub>H</sub> , at 50 °C)  Motor feeder  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 5	Braking function			
Braking torque with external braking resistance minimum external braking resistance  Reference voltage  Max. 100% of rated operational current I <sub>Q</sub> with external braking resistor  Work  Control section  Reference voltage  Us V 10 V DC (max. 10 mA)  Analog inputs  Analog outputs  Digital inputs  Digital inputs  Releave outputs  Inputs  Inputs  Releave outputs  Inputs  I	Standard braking torque			max. 30 % M <sub>N</sub>
minimum external braking resistance  Switch-on threshold for the braking transistor  Upc V 780 V DC  Control section  Reference voltage  Us V 10 V DC (max. 10 mA)  Analog inputs  Analog outputs  Digital inputs  Digital inputs  Digital outputs	DC braking torque			adjustable to 100 %
Switch-on threshold for the braking transistor         UDC         V         780 V DC           Control section         Reference voltage         Us         V         10 V DC (max. 10 mA)           Analog inputs         2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA           Analog outputs         1, parameterizable, 0 - 10 V DC, 0/4 - 20 mA           Digital inputs         4, parameterizable, 0 - 10 V           Digital outputs         1, parameterizable, max. 30 V DC           Digital outputs         1, parameterizable, 24 V DC           Relay outputs         1, parameterizable, NVO, 6 A (250 V, AC-1) / 5 A (30 V, DC-1)           Interface/field bus (built-in)         0P-Bus (RS485)/Modbus RTU, CANopen®           Assigned switching and protective elements         FAZ-B16/3           UL (Class CC or J)         A         15           150 % overload (CT/l <sub>H</sub> , at 50 °C)         A         15           Motor feeder         DX-LN3-016           150 % overload (CT/l <sub>H</sub> , at 50 °C)         DX-LN3-011           150 % overload (CT/l <sub>H</sub> , at 50 °C)         DX-LN3-010           150 % overload (CT/l <sub>H</sub> , at 50 °C)         DX-BR100-0K8           150 % overload (CT/l <sub>H</sub> , at 50 °C)         DX-BR100-0K8	Braking torque with external braking resistance			Max. 100% of rated operational current l <sub>e</sub> with external braking resistor
Control section  Reference voltage  Us V 10 V DC (max. 10 mA)  2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA  Analog inputs  Analog outputs  1, parameterizable, 0 - 10 V DC  1, parameterizable, 24 V DC  1, parameterizable, 24 V DC  1, parameterizable, 24 V DC  1, parameterizable, N/0, 6 A (250 V, AC-1) / 5 A (30 V, DC-1)  Interface/field bus (built-in)  Assigned switching and protective elements  Power Wiring  IEC (Type B, g6), 150 %  UL (Class CC or J)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  Motor feeder  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  DX-LN3-016  DX-LN3-010  DX-SIN3-010  DX-SIN3-010  DX-BR100-0K8  DX-BR100-0K8  DX-BR100-1K6	minimum external braking resistance	R <sub>min</sub>	Ω	100
Reference voltage  Us V 10 V DC (max. 10 mA)  2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA  Analog inputs Analog outputs 1, parameterizable, 0 - 10 V DC (max. 30 V DC  1, parameterizable, 0 - 10 V DC, 0/4 - 20 mA  4, parameterizable, 0 - 10 V DC  1, parameterizable, max. 30 V DC  1, parameterizable, 24 V DC  Relay outputs	Switch-on threshold for the braking transistor	U <sub>DC</sub>	V	780 V DC
Analog inputs Analog outputs Digital inputs Digital inputs Digital outputs Dig	Control section			
Analog outputs  Digital inputs  Digital inputs  Digital outputs  A, parameterizable, max. 30 V DC  1, parameterizable, max. 30 V DC  1, parameterizable, 24 V DC  Relay outputs  1, parameterizable, N/O, 6 A (250 V, AC-1) / 5 A (30 V, DC-1)  Interface/field bus (built-in)  Assigned switching and protective elements  Power Wiring  IEC (Type B, gG), 150 %  LU (Class CC or J)  A 15  150 % overload (CT/I <sub>H</sub> , at 50 °C)  Motor feeder  150 % overload (CT/I <sub>H</sub> , at 50 °C)  DX-LN3-016  Motor feeder  150 % overload (CT/I <sub>H</sub> , at 50 °C)  DX-SIN3-010  DX-SIN3-010  DX-SIN3-010  DX-BR100-0K8  DX-BR100-1K6	Reference voltage	U <sub>s</sub>	V	10 V DC (max. 10 mA)
Digital inputs  A, parameterizable, max. 30 V DC  1, parameterizable, 24 V DC  Relay outputs  1, parameterizable, 24 V DC  Relay outputs  1, parameterizable, N/O, 6 A (250 V, AC-1) / 5 A (30 V, DC-1)  Interface/field bus (built-in)  Assigned switching and protective elements  Power Wirring  IEC (Type B, gG), 150 %  IEC	Analog inputs			2, parameterizable, 0 - 10 V DC, 0/4 - 20 mA
Digital outputs Relay outputs 1, parameterizable, 24 V DC 1, parameterizable, N/O, 6 A (250 V, AC-1) / 5 A (30 V, DC-1) Interface/field bus (built-in)  Assigned switching and protective elements  Power Wirring  IEC (Type B, gG), 150 %  UL (Class CC or J)  A 15  150 % overload (CT/I <sub>H</sub> , at 50 °C)  Motor feeder  150 % overload (CT/I <sub>H</sub> , at 50 °C)  DX-LM3-016  DX-LM3-011  150 % overload (CT/I <sub>H</sub> , at 50 °C)  DX-LM3-010  DX-SIN3-010  DX-SIN3-010  DX-BR100-0K8  DX-BR100-1K6	Analog outputs			1, parameterizable, 0 - 10 V
Relay outputs Interface/field bus (built-in)  Assigned switching and protective elements  Power Wiring  IEC (Type B, gG), 150 %  UL (Class CC or J)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> ,	Digital inputs			4, parameterizable, max. 30 V DC
Interface/field bus (built-in)  Assigned switching and protective elements  Power Wiring  IEC (Type B, gG), 150 %  UL (Class CC or J)  A 15  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  10 % Einschaltdauer (ED)  10 % Binschaltdauer (ED)  10 % Binschaltdauer (DF)  10 % Binschaltdauer (DF)	Digital outputs			1, parameterizable, 24 V DC
Assigned switching and protective elements    IEC (Type B, gG), 150 %	Relay outputs			1, parameterizable, N/O, 6 A (250 V, AC-1) / 5 A (30 V, DC-1)
Power Wiring         FAZ-B16/3           IEC (Type B, gG), 150 %         FAZ-B16/3           UL (Class CC or J)         A         15           150 % overload (CT/I <sub>H</sub> , at 50 °C)         DX-LN3-016           Motor feeder         DX-LN3-016           150 % overload (CT/I <sub>H</sub> , at 50 °C)         DX-LM3-011           150 % overload (CT/I <sub>H</sub> , at 50 °C)         DX-SIN3-010           10 % Einschaltdauer (ED)         DX-BR100-0K8           20 % duty factor (DF)         DX-BR100-1K6	Interface/field bus (built-in)			OP-Bus (RS485)/Modbus RTU, CANopen®
IEC (Type B, gG), 150 %       FAZ-B16/3         UL (Class CC or J)       A       15         150 % overload (CT/I <sub>H</sub> , at 50 °C)       DX-LN3-016         Motor feeder       DX-LN3-011         150 % overload (CT/I <sub>H</sub> , at 50 °C)       DX-SIN3-010         150 % overload (CT/I <sub>H</sub> , at 50 °C)       DX-SIN3-010         10 % Einschaltdauer (ED)       DX-BR100-0K8         20 % duty factor (DF)       DX-BR100-1K6	Assigned switching and protective elements			
UL (Class CC or J)       A       15         150 % overload (CT/I <sub>H</sub> , at 50 °C)       DX-LN3-016         Motor feeder       DX-LM3-011         150 % overload (CT/I <sub>H</sub> , at 50 °C)       DX-SIN3-010         150 % overload (CT/I <sub>H</sub> , at 50 °C)       DX-SIN3-010         10 % Einschaltdauer (ED)       DX-BR100-0K8         20 % duty factor (DF)       DX-BR100-1K6	Power Wiring			
150 % overload (CT/I <sub>H</sub> , at 50 °C)       DX-LN3-016         Motor feeder       DX-LM3-011         150 % overload (CT/I <sub>H</sub> , at 50 °C)       DX-LM3-011         150 % overload (CT/I <sub>H</sub> , at 50 °C)       DX-SIN3-010         10 % Einschaltdauer (ED)       DX-BR100-0K8         20 % duty factor (DF)       DX-BR100-1K6	IEC (Type B, gG), 150 %			FAZ-B16/3
Motor feeder  150 % overload (CT/I <sub>H</sub> , at 50 °C)  150 % overload (CT/I <sub>H</sub> , at 50 °C)  DX-SIN3-010  DX-SR100-0K8  20 % duty factor (DF)  DX-BR100-1K6	UL (Class CC or J)		Α	15
DX-LM3-011  150 % overload (CT/I <sub>H</sub> , at 50 °C)  DX-SIN3-010  DX-SR100-0K8  DX-BR100-1K6	150 % overload (CT/I <sub>H</sub> , at 50 °C)			DX-LN3-016
150 % overload (CT/I <sub>H</sub> , at 50 °C)  10 % Einschaltdauer (ED)  20 % duty factor (DF)  DX-SIN3-010  DX-BR100-0K8  DX-BR100-1K6	Motor feeder			
10 % Einschaltdauer (ED)  DX-BR100-0K8  20 % duty factor (DF)  DX-BR100-1K6	150 % overload (CT/I $_{\rm H}$ , at 50 °C)			DX-LM3-011
20 % duty factor (DF) DX-BR100-1K6	150 % overload (CT/I <sub>H</sub> , at 50 °C)			DX-SIN3-010
	10 % Einschaltdauer (ED)			DX-BR100-0K8
40 % duty factor (DF) DX-BR100-6K2	20 % duty factor (DF)			DX-BR100-1K6
	40 % duty factor (DF)			DX-BR100-6K2

# Design verification as per IEC/EN 61439

Technical data for design verification			
Rated operational current for specified heat dissipation	In	Α	9.5
Heat dissipation per pole, current-dependent	$P_{vid}$	W	0
Equipment heat dissipation, current-dependent	$P_{\text{vid}}$	W	136
Static heat dissipation, non-current-dependent	$P_{vs}$	W	0
Heat dissipation capacity	P <sub>diss</sub>	W	0
Operating ambient temperature min.		°C	-10
Operating ambient temperature max.		°C	50

EC/EN 61439 design verification	
10.2 Strength of materials and parts	
10.2.2 Corrosion resistance	Meets the product standard's requirements.
10.2.3.1 Verification of thermal stability of enclosures	Meets the product standard's requirements.
10.2.3.2 Verification of resistance of insulating materials to normal heat	Meets the product standard's requirements.
10.2.3.3 Verification of resistance of insulating materials to abnormal heat and fire due to internal electric effects	Meets the product standard's requirements.
10.2.4 Resistance to ultra-violet (UV) radiation	Meets the product standard's requirements.
10.2.5 Lifting	Does not apply, since the entire switchgear needs to be evaluated.
10.2.6 Mechanical impact	Does not apply, since the entire switchgear needs to be evaluated.
10.2.7 Inscriptions	Meets the product standard's requirements.
10.3 Degree of protection of ASSEMBLIES	Does not apply, since the entire switchgear needs to be evaluated.
10.4 Clearances and creepage distances	Meets the product standard's requirements.
10.5 Protection against electric shock	Does not apply, since the entire switchgear needs to be evaluated.
10.6 Incorporation of switching devices and components	Does not apply, since the entire switchgear needs to be evaluated.
10.7 Internal electrical circuits and connections	Is the panel builder's responsibility.
10.8 Connections for external conductors	Is the panel builder's responsibility.
10.9 Insulation properties	
10.9.2 Power-frequency electric strength	Is the panel builder's responsibility.
10.9.3 Impulse withstand voltage	Is the panel builder's responsibility.
10.9.4 Testing of enclosures made of insulating material	Is the panel builder's responsibility.
10.10 Temperature rise	The panel builder is responsible for the temperature rise calculation. Eaton will provide heat dissipation data for the devices.
10.11 Short-circuit rating	Is the panel builder's responsibility. The specifications for the switch gear must be observed. $\label{eq:constraint}$
10.12 Electromagnetic compatibility	Is the panel builder's responsibility. The specifications for the switchgear must be observed.
10.13 Mechanical function	The device meets the requirements, provided the information in the instruction leaflet (IL) is observed.

#### **Technical data ETIM 6.0**

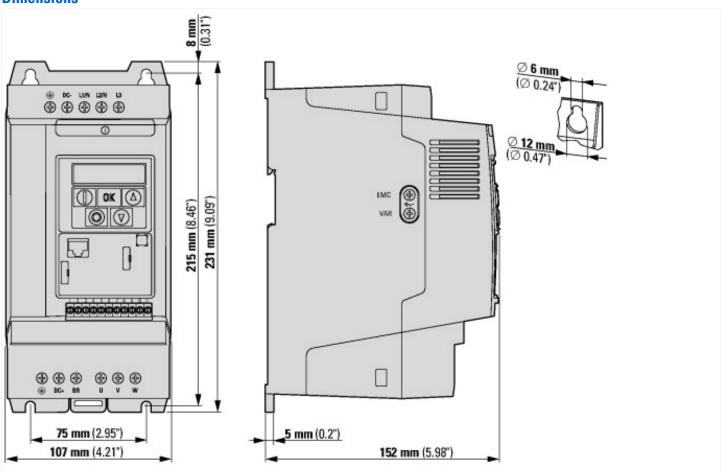
Technical data ETTIVI 6.0		
Low-voltage industrial components (EG000017) / Frequency converter =< 1 kV (EC	001857)	
Electric engineering, automation, process control engineering / Electrical drive /	Static frequency converte	r / Static frequency converter = < 1 kv (ecl@ss8.1-27-02-31-01 [AKE177011])
Mains voltage	V	380 - 480
Mains frequency		50/60 Hz
Number of phases input		3
Number of phases output		3
Max. output frequency	Hz	500
Max. output voltage	V	400
Rated output current I2N	А	9.5
Max. output at quadratic load at rated output voltage	kW	4
Max. output at linear load at rated output voltage	kW	4
With control unit		Yes
Application in industrial area permitted		Yes
Application in domestic- and commercial area permitted		Yes
Supporting protocol for TCP/IP		No
Supporting protocol for PROFIBUS		No
Supporting protocol for CAN		Yes
Supporting protocol for INTERBUS		No
Supporting protocol for ASI		No
Supporting protocol for KNX		No
Supporting protocol for MODBUS		Yes
Supporting protocol for Data-Highway		No
Supporting protocol for DeviceNet		No
Supporting protocol for SUCONET		No
Supporting protocol for LON		No
Supporting protocol for PROFINET IO		No

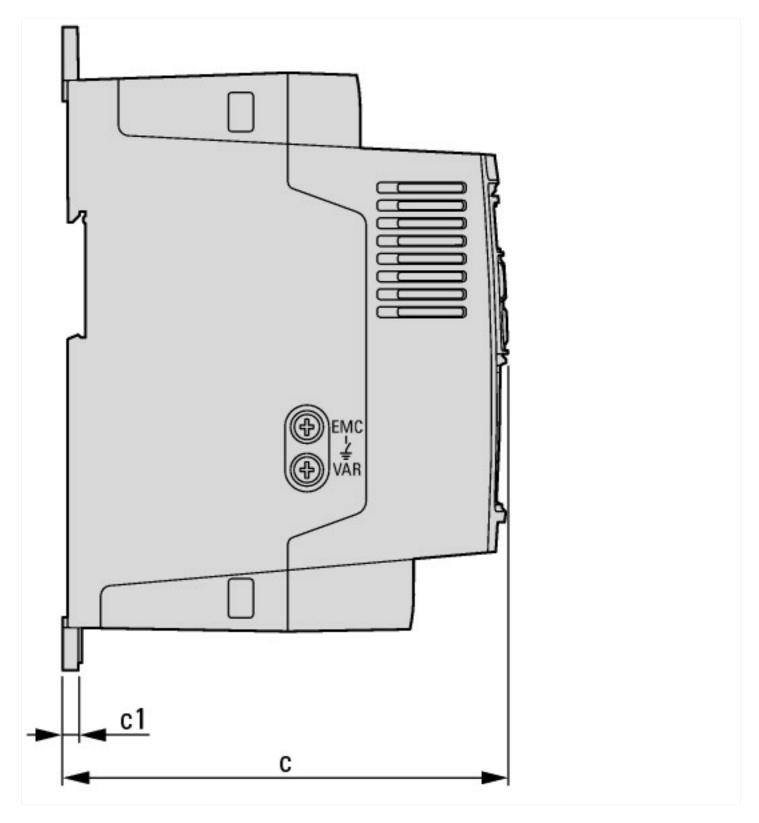
	No
	No
	0
	0
	0
	0
	1
	0
	1
	0
	0
	No
	Yes
	Yes
	No
	U converter
	IP20
mm	231
mm	107
mm	152
%	10
%	10
	mm mm %

## Approvals

UL 508C; CSA-C22.2 No. 14; IEC/EN61800-3; IEC/EN61800-5; CE marking
E172143
NMMS, NMMS7
UL report applies to both US and Canada
UL listed, certified by UL for use in Canada
No
Branch circuits
3~ 480 V AC IEC: TN-S UL/CSA: "Y" (Solidly Grounded Wey)
IEC: IP20

#### **Dimensions**





#### Additional product information (links)

Additional product information (miks)					
IL04020009Z DC1 variable frequency drives (FS1 - FS3, IP20)					
IL04020009Z DC1 variable frequency drives (FS1 - FS3, IP20)	ftp://ftp.moeller.net/DOCUMENTATION/AWA_INSTRUCTIONS/IL04020009Z2016_07.pdf				
MN04020003Z DC1 variable frequency drives, l	MN04020003Z DC1 variable frequency drives, Installation manual				
MN04020003Z Frequenzumrichter DC1, Handbuch - Deutsch	ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020003Z_DE.pdf				
MN04020003Z DC1 variable frequency drive, manual - English	ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020003Z_EN.pdf				
MN04020003Z Frekvenční měnič DC1, manuál - čeština	ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020003Z_CZ.pdf				
MN04020003Z Convertitori di frequenza DC1, manuale - italiano	ftp://ftp.moeller.net/DOCUMENTATION/AWB_MANUALS/MN04020003Z_IT.pdf				
MN04020004Z DC1 variable frequency drives, Parameters manual					
MNI040200047 DC1 variable frequency drives	tra//ftp.moollor.pot/DOCIMENTATION/AWR_MANUALS/MN040200047_DE.pdf				

MN04020004Z DC1 variable frequency drives, ftp://ftp.moeller.net/DOCUMENTATION/AWB\_MANUALS/MN04020004Z\_DE.pdf Parameters manual - Deutsch

MN04020004Z DC1 variable frequency drives, Parameters manual - English ftp://ftp.moeller.net/DOCUMENTATION/AWB\_MANUALS/MN04020004Z\_EN.pdf CA04020001Z-DE Sortimentskatalog: Antriebstechnik effizient gestalten, Motoren starten und steuern  $http://www.eaton.eu/DE/ecm/groups/public/@pub/@europe/@electrical/documents/content/pct\_1095238\_de.pdf$